

**Student Name: Student Number:** 

**Dept. of Computer Engineering** Second Exam, Second Semester: 2006/2007

Course Title: Neural Networks & Fuzzy Logic	Date: 17/5/2007
Course No: (630551)	Time Allowed: 1 Hour
Lecturer: Dr. Mohammed Mahdi	No. of Pages: 1

## **Question 1:**

(8 Marks)

## **Objectives:**

This question is about fuzzy-logic control system design.

Given a scaled and unified U.O.D for the input signals E, CE, and output signal U from – 2.5 to + 2.5 of 5-quantized levels. With three fuzzy sets of N, Z, P of triangular distribution (assume fuzzy member ships). For a certain input state of E = -3.0 and CE = -2.5, apply Mamdani fuzzy logic control style to find the related crisp control action when centre of gravity fuzzifier is used. Discuss your answer.

## Question 2:

(12 Marks)

## **Objectives:**

This question is about Hopfield neural network and the concepts of Fuzzy Logic.

Answer the following with Yes or No giving the reason: -

- There is no need for lengthy training in Hopfield neural network. \*
- The number of units in Hopfield neural network has an effect on the number \* of patterns that can be stored.
- Stability of the network can be tested when cued with non-stored pattern. \*
- Hopfield neural network activation function can be considered as a hard limiter. \*
- Fuzzy logic does not need a mathematical model. \*
- Fuzzifier is considered as a converter form fuzzy domain to crisp value domain. \*
- Switching line in the FPR's table does not always exist. \*
- Centre of Gravity formula finds the effective point that represents the effect of an \* n-element vector.